### $K_7$ in the torus: a long story

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- 2. Cayley graphs and Cayley maps
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I am mostly interested in the last item.

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### Rotation systems

To define an orientable embedding for a graph G, we only need to give for each vertex v a cyclic order of the edges incident to v, that would be induced by an orientation of the embedding surface. The collection of all these cyclic orders is called a **rotation system**. To see the embedding surface associated with a rotation system, just thicken each vertex to a disk, thicken each edge to a band and attach around each vertex-disk by the order given by the rotation. The result is a thickening of the graph to a surface with boundary.

### Rotation systems

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The idea os specifying an embedding for a given graph G this way is due to Heffter (1895) and Edmonds(1956). Important

observation: any graph automorphism that respects the rotation (cyclic order at each vertex) induces an automorphism of the embedding (takes faces to faces).

The idea is to describe an embedding (or "map") with lots of symmetry.

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Orientably regular maps are analagous to the Platonic solids, having full rotation symmetry at every vertex, every face-center, and every edge-midpoint.

An orientably regular map may also have orientation-reversing "reflection". If so it is called **reflexible**; if not it is **chiral**.

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#### Theorem

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- 2. Show they are all chiral for n > 4.
- 3. Deal with non-orientable maps

### Classifying all orientably regular maps for $K_n$

First, the  $K_7$  map generalizes to any finite fields GF(q), where  $q = p^n$ . Let x generate the cyclic multiplicative group. The additive group is abelian  $A = Z_p^n$ . The Cayley map  $CM(A, (1, x, x^2, x^3, \dots x^{q-2} \text{ is is regular.})$ 

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#### Theorem

The only orientably regular maps with underlying  $K_n$  are the finite field maps.

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Thus every element of A has the same order, which therefore must be a prime p; and the only characteristic subgroups are trivial, making A abelian. So  $A = Z_p^n$  and mult by y is linear transformation with irred minimal poly of degree n etc.

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Theorem

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Note this handles also the non-orientable case of  $K_6$ . Also it says far more. And the proof is almost trivial!

### Angle measure

The idea comes from maps, where each vertex has a natural cyclic order coming from a local orientation of the surface. We will show later how this works out when we only have a group A where the actions of  $A_v$  are naturally dihedral.

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Suppose that the cyclic order of vertices adjacent to v is  $u_1, u_2, \dots u_d$ , where d is the valence of v. Then we call  $u_i v u_j$  an **angle** at v with **measure**  $m(u_i v u_j)$  either |i - j| or d - |i - j|, whichever is smaller. In particular,  $m(u_i v u_j) \leq d/2$ .

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## The proof

Let M be a regular (reflexible) map. We observe that since automorphisms respect (or reverse) local orientations, they preserve angle measure.

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It follows that if *uvw* is triangle (3-cycle), then the reflection at v means m(vuw) = m(wvu). Since this is true at each vertex, the triangle *uvw* is equiangular, namely m(uvw) = m(vwu) = m(wuv).

Suppose now that u, v, w, x induce  $K_4$ . There are three angles at u. Suppose their measures are:

$$m(vuw) = a, m(wux) = b, m(xuv) = c, where a \le b \le c.$$

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d - (a + b) = c, d - (b + c) = a, d - (c + a) = b. Since all triangles are equiangular, we have a = b = c = d/3.

### Consequences of a = b = c

We have all  $K_4$  subgraphs are symmetrically situated at every vertex making angles a = b = c = d/3. In particular, each edge can be in one and only one  $K_4$ .

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So a = b, 2c + a = d, a = d/5, c = 2d/5
Consequences of a = b = d/5, c = 2d/5

By the circular symmetry around a vertex, we must have a  $K_6$  making all angles d/5 at any vertex.

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Again every edge is in one and only one  $K_6$ , so G has no  $K_7$  and G has a  $K_6$  factorization

### Non-orientability for the $K_6$ case

Let  $B \subset Aut(M)$  be the subgroup stabilizing a  $K_6$  subgraph  $H \subset G$ . By the 5-fold dihedral symmetry at each vertex of H, we have  $|H| = 10 \cdot 6 = 60$ .

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But if M were orientable, the orientation-preserving elements of B would form a subgroup of index two, a contradiction (Note: H contains reflections, so H is is not orientation-preserving.)

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This cyclic order at each vertex can now be used to define an angle measure that is invariant under *A*, allowing us to apply the previous map argument.

For  $K_4$ , there is the family of groups from Conder, Širà ň, Tucker (JEMS 2010):  $G(3,3,n) = \langle X, Y : X^{3n} = Y^{3n} = (XY)^2 = 1, X^{12}Y^{12} = 1 \rangle$ 

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For  $K_6$ , a similar construction works with the groups  $G(3,5,n) = \langle X, Y : X^{3n} = Y^{5n} = (XY)^2 = 1, X^{60}Y^{60} = 1 \rangle$ Marston Conder has found, with the help of Magma, a family of infinitely many examples for  $K_4$  where the underlying graph has no multiple edges. Same for  $K_6$ .